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# Double Half-Bridge Submodule based Modular Multilevel Converters with Reduced Voltage Sensors

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**Abstract-** The half-bridge (HB) submodule (SM) based MMC requires a large number of sensors to measure capacitor voltages. In this letter, a double half-bridge (DHB) SM based MMC is proposed, where each SM consists of two HBs. But only one voltage sensor is equipped in each DHB-SM for capacitor voltage estimation, which is connected between positive poles of two capacitors in the DHB-SM. A capacitor voltage estimation method is also proposed, which can estimate capacitor voltages in the proposed MMC with only a half number of voltage sensors in comparison with HB-SM based MMCs. A DHB-SM based three-phase MMC is simulated with PSCAD/EMTDC and A DHB-SM based single-phase MMC prototype is built in laboratory. Both the simulation and experimental results confirm the effectiveness of the proposed method.

**Index terms-** Half bridge, modular multilevel converters, voltage sensor, submodule.

## I. INTRODUCTION

The modular multilevel converters (MMCs) have received great interests from both academic and industry due to its advantages like easy construction, flexibility in converter design, excellent output voltage, high efficiency [1-5], etc.

In conventional HB-SM based MMCs, a large number of sensors are equipped to measure the capacitor voltages, where the number of voltage sensor is the same to that of the submodule (SM) [6]. Recently, a number of studies are focused on reducing voltage sensors in MMCs, which can be divided into three categories, including software-based methods, hardware-based methods and fix pattern-based methods.

In software-based methods, the SM capacitor voltages are estimated through the system dynamics along with a number of extra sensors. The individual capacitor voltages can be estimated with weighted recursive least square algorithm [7] or Kalman Filter [8], where extra voltage sensors are equipped to measure the arm voltages. Similarly, an adaptive linear neuron algorithm is used in [9], where the voltages on the arm inductors are measured by extra voltage sensors. In [10], the output voltages of SM groups are measured by sensors, and the capacitor voltages can be obtained when only one SM is

activated in the SM group. A capacitor voltage estimation with capacitance self-updating based on grouping measurement is presented in [11], which increases the accuracy of the voltage estimation. Even no extra sensors are applied, the capacitor voltages can be estimated with adaptive observers [12] or Kalman Filters [13]. The main limitations of the software-based methods are: 1) Computational burden is explosively increased along with the increase of number of SMs, which limits its application to MMCs with small number of SMs. 2) High voltage sensors or sensors with high galvanic isolation voltage are required.

In hardware-based methods, extra semiconductor devices are equipped to balance the SM capacitor voltages. A diode-clamp MMC with SM voltage self-balancing ability is presented in [14], where two adjacent capacitors can be paralleled through the clamping diode. To limit the balancing current, small inductors are connected in series with the clamping diodes in a diode-clamp MMC based STATCOM [15] and a diode-clamp MMC based DC transformer [16]. In [17], additional two diodes are used for symmetrical HB-SM to achieve sensorless voltage balance. A semi-full-bridge SM is presented in [18], where two capacitors can be connected in parallel through the conducted insulated gate bipolar transistors (IGBTs). In [19], a reduced series/parallel module are presented for cascaded multilevel converter, which can be configured in series, bypassed or in parallel to balance all capacitor voltages in a sensorless manner. The number of voltage sensors can be reduced by hardware-based methods, which also reduces the communication burden and computational burden in regards of the voltage balancing controls [20]. However, the limitations of the hardware-based methods are evident: 1) The balancing current would be large when the voltage deviation between two paralleled capacitors is large, especially during the startup process, which requires semiconductor devices with big capability. 2) Extra devices not only lead to extra losses but it will also increase the costs.

In fix pattern-based methods, the SMs are switched into a fixed pattern that the power absorbed by each SM is equal. A fix pulse pattern with harmonic elimination is presented in [21], where the stored energy in each SM remains stable. A hierarchical permutation cyclic coding method can evenly distribute the switching gate signals among the SMs [22] and the SM capacitor voltages can be balanced in a wide range of switching frequencies. A Y-Matrix Modulation method is presented in [23], where MMCs can achieve self-voltage balancing without measurements and feedback controls. However, in practical systems, the power losses of SMs can be various due to manufacturing errors [24] or different leakage resistances in valve tower [25]. The fix pattern-based methods cannot ensure an exact voltage balancing.

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This letter proposes a double half-bridge (DHB) SM based MMC, where only a voltage sensor is equipped between positive poles of two capacitors in each DHB-SM. In addition, the corresponding capacitor voltage estimation method is also proposed for each DHB-SM with a simple algorithm. The proposed DHB-SM based MMC only requires a half number of voltage sensors in comparison with the conventional HB-SM based MMC [6].

The rest of letter is organized as follows. The proposed DHB-SM based MMCs and capacitor voltage estimation methods are presented in Section II and Section III, respectively. The simulation and experimental studies are presented in Section IV and Section V, respectively. Finally, the conclusions are drawn in Section VI.

### II. PROPOSED DHB-SM BASED MMCs

A single-phase DHB-SM based MMC is shown in Fig. 1(a), which consists of an upper arm and a lower arm. Each arm consists of  $N$  identical DHB-SMs and an inductor  $L_s$ . Fig. 1(b) shows the  $i$ -th ( $i=1, 2, \dots, N$ ) DHB-SM in the upper arm, which is composed of two HBs (HB<sub>i1</sub> & HB<sub>i2</sub>) connected in series. The HB<sub>ij</sub> ( $j=1, 2$ ) consists of two switches ( $T_{uij}, T_{lij}$ ) and one capacitor  $C_{ij}$ , which are controlled by the switching function  $S_{ij}$  as listed in Table I. When  $S_{ij}=1$ ,  $T_{uij}$  is on and  $T_{lij}$  is off. Here, the capacitor  $C_{ij}$  is inserted into the arm and capacitor voltage  $u_{cij}$  is increased with positive arm current and decreased with negative arm current. When  $S_{ij}=0$ ,  $T_{uij}$  is off and  $T_{lij}$  is on. The capacitor  $C_{ij}$  is bypassed from the arm, and  $u_{cij}$  is unchanged.

One thing to mention is that, only one voltage sensor is used between the positive poles of two capacitors in each DHB-SM to estimate capacitor  $C_{i1}$ 's voltage and  $C_{i2}$ 's voltage, which will be discussed more in Section III.

TABLE I  
Switching States of HB<sub>ij</sub>

$S_{ij}$	$T_{uij}$	$T_{lij}$	$i_{au}$	$u_{cij}$
1	on	off	Positive	Increase
			Negative	Decrease
0	off	on	Positive	Unchange
			Negative	Unchange

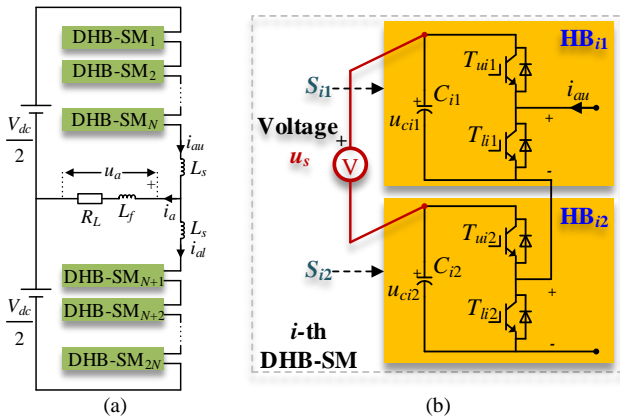


Fig. 1 (a) Single-phase DHB-SM based MMC. (b) Topology of  $i$ -th DHB-SM.

TABLE II  
Relationship between  $S_{i2}$  and  $u_s$

$S_{i2}$	$u_s$
1	$u_{ci1}$
0	$u_{ci1} - u_{ci2}$

### III. PROPOSED CAPACITOR VOLTAGE ESTIMATION METHOD FOR DHB-SMs BASED MMCs

#### A. Sensor's Measurement Voltage

In the  $i$ -th DHB-SM, as shown in Fig. 1(b), only one voltage sensor is equipped to estimate capacitor voltage  $u_{ci1}$  and  $u_{ci2}$ . The measurement voltage  $u_s$  obtained from the sensor depends on the  $S_{i2}$  corresponding to HB<sub>i2</sub>, as listed in Table II.

- 1)  $S_{i2}=1$ : the sensor is connected in parallel with the  $C_{i1}$ , as depicted in Fig. 2(a). Here,  $u_s = u_{ci1}$ .
- 2)  $S_{i2}=0$ : the negative poles of  $C_{i1}$  and  $C_{i2}$  are connected together, as depicted in Fig. 2(b). Here, the  $u_s$  equals to the voltage deviation  $\Delta u_{ci}$  between  $C_{i1}$ 's voltage  $u_{ci1}$  and  $C_{i2}$ 's voltage  $u_{ci2}$ , as  $u_s = \Delta u_{ci} = u_{ci1} - u_{ci2}$ .

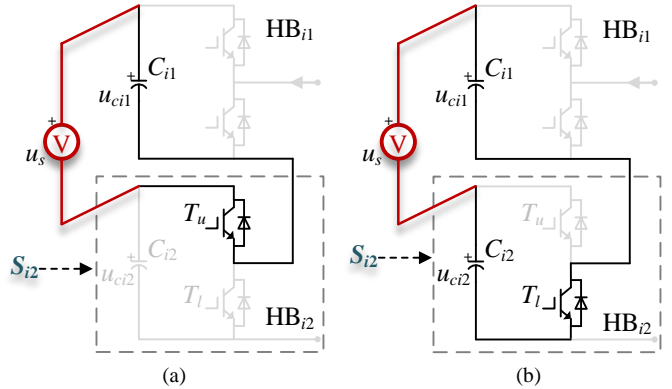


Fig. 2. Sensor voltage  $u_s$  corresponding to  $S_{i2}$  of HB<sub>i2</sub>. (a)  $S_{i2} = 1$ . (b)  $S_{i2} = 0$ .

#### B. Proposed Capacitor Voltage Estimation Method

Based on the above analysis, a capacitor voltage estimation method is proposed. Fig. 3 shows the proposed capacitor voltage estimation method for the  $i$ -th DHB-SM in the upper arm. In Fig. 3(a), the SM individual voltage balancing control method [26] including voltage balancing control (VBC) and voltage average control (VAC) is employed for the MMC. With the ac-side voltage reference  $u_a^*$ , estimated capacitor voltage  $\hat{u}_{ci1}$  and  $\hat{u}_{ci2}$ , and average capacitor voltage  $u_{c\_ave}$  in the phase, the reference signals  $y_{i1}$  and  $y_{i2}$  can be produced and compared with two carriers to generate the switching functions  $S_{i1}$  and  $S_{i2}$  for the HB<sub>i1</sub> and HB<sub>i2</sub> in the  $i$ -th DHB-SM, respectively, which can ensure the capacitor voltage balancing in the MMC and it is close to the rated SM capacitor voltage  $u_{c0}$  as

$$u_{c0} = V_{dc}/(2N). \quad (1)$$

In Fig. 3, the average capacitor voltage  $u_{c\_ave}$  is

$$u_{c\_ave} = \sum_{i=1}^{2N} (\hat{u}_{ci1} + \hat{u}_{ci2}) / (4N) \quad (2)$$

In the MMC, the phase-shifted carrier (PSC) based pulse width modulation (PWM) technique is adopted. The  $2N$  isosceles triangle carriers with the phase-shifted angle of  $\pi/N$  are employed for SMs in the upper arm, where the carrier period is  $T_s$  and angular frequency is  $\omega_s = 2\pi/T_s$ . In Fig. 3(a), the initial phase angle of carrier  $W_{i2}$  for the HB<sub>i2</sub> in the  $i$ -th DHB-SM is

$$\theta_{i2} = (2i-1) \cdot \pi/N. \quad (3)$$

Fig. 3(b) shows the detailed modulation for the HB<sub>i2</sub>. The  $S_{i2}$  is generated based on the  $y_{i2}$  and  $W_{i2}$  as

- $S_{i2}=1$  if  $y_{i2} > W_{i2}$

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- $S_{i2}=0$  if  $y_{i2}<W_{i2}$

As a result, Table III can be easily obtained as

- $S_{i2}=1$  at the valley of  $W_{i2}$  and this instant is

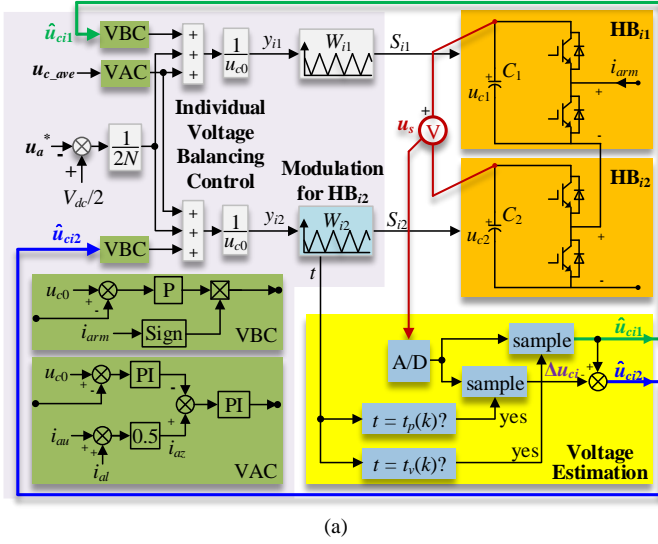
$$t_v(k) = \frac{\theta_{i2}}{\omega_s} + (k + \frac{1}{2}) \cdot T_s = (\frac{2i-1}{2N} + k + \frac{1}{2}) \cdot T_s, \quad (k=0,1,2,\dots) \quad (4)$$

- $S_{i2}=0$  at the peak of  $W_{i2}$  and this instant is

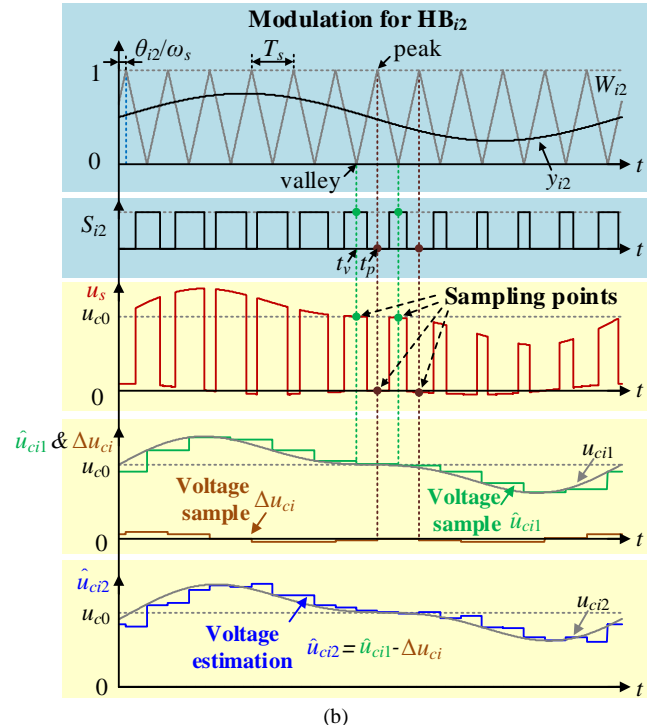
$$t_p(k) = \frac{\theta_{i2}}{\omega_s} + k \cdot T_s = (\frac{2i-1}{2N} + k) \cdot T_s, \quad (k=0,1,2,\dots) \quad (5)$$

TABLE III  
Relationship among  $t$ ,  $W_{i2}$  and  $S_{i2}$

$t$	$W_{i2}$	$S_{i2}$
$t_v(k) = [(2i-1)/(2N) + k + 1/2] \cdot T_s$	Valley	1
$t_p(k) = [(2i-1)/(2N) + k] \cdot T_s$	Peak	0



(a)



(b)

Fig. 3. Proposed capacitor voltage estimation method. (a) Capacitor voltage estimation for the  $i$ -th DHB-SM. (b) Proposed synchronous sampling.

Based on Tables II and III, the capacitor voltage  $u_{ci1}$  of  $C_{i1}$  and  $u_{ci2}$  of  $C_{i2}$  can be sampled and estimated from the sensor voltage  $u_s$ , where the sampling of the sensor voltage  $u_s$  and the estimation of capacitor voltage are synchronized with the carrier  $W_{i2}$  for HB <sub>$i2$</sub> , as follows.

- 1) Estimation of voltage  $\hat{u}_{ci1}$  for  $C_{i1}$

$\hat{u}_{ci1}$  is periodically sampled from sensor voltage  $u_s$  at the time  $t_v(k)$  with period of  $T_s$ , as shown in Fig. 3(b), given as

$$\hat{u}_{ci1} = u_s(t)|_{t=t_v(k)} \quad (6)$$

- 2) Estimation of voltage  $\hat{u}_{ci2}$  for  $C_{i2}$

The voltage deviation  $\Delta u_c$  is periodically sampled from sensor voltage  $u_s$  at the time  $t_p(k)$  with period of  $T_s$ , as shown in Fig. 3(b), as

$$\Delta u_{ci} = u_s(t)|_{t=t_p(k)} \quad (7)$$

As a result, the  $\hat{u}_{ci2}$  can be estimated as

$$\hat{u}_{ci2} = \hat{u}_{ci1} - \Delta u_{ci} \quad (8)$$

## IV. SIMULATION STUDIES

To verify the effectiveness of the proposed method, a three-phase DHB-SM based MMC (12 DHB-SMs per arm) is simulated with PSCAD/EMTDC, while a three-phase HB-SM based MMC (24 HB-SMs per arm) is also simulated for comparison. The diagram of the simulated system is shown in Fig. 4 and the system parameters are listed in TABLE IV. Initially, the active power  $P$  and the reactive power  $Q$  are regulated at 18 MW and 0 MVar, respectively. At 2.5 s,  $P$  is reduced to 9 MW in a step and  $Q$  is not changed.

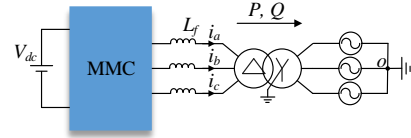


Fig. 4. Diagram of the simulated system.

TABLE IV  
Parameters for Simulated System

Parameter	Value
Rated power (MW)	20
DC link voltage $V_{dc}$ (kV)	24
Rated frequency (Hz)	50
Grid line-to-line voltage	33 kV
Transformer voltage rating	12 kV/33 kV
Rated capacitor voltage $u_{c0}$ (kV)	1
SM capacitance (mF)	15
Arm inductance $L_s$ (mH)	4
Filter inductance $L_f$ (mH)	1
Carrier frequency $1/T_s$ (Hz)	110

### A. Case I: DHB-SM based MMC

Figs. 5~7 show the performance of the proposed DHB-SM based MMC. Fig. 5 shows the ac-side current  $i_a$ ,  $i_b$  and  $i_c$ . Fig. 6(a) shows the estimated capacitor voltage  $\hat{u}_{ci1}$  and capacitor voltage  $u_{ci1}$  for  $C_{i1}$  in HB <sub>$i1$</sub>  of DHB-SM<sub>1</sub> in upper arm of phase A. Fig. 6(b) shows the estimated capacitor voltage  $\hat{u}_{ci2}$  and capacitor voltages  $u_{ci2}$  for  $C_{i2}$  in HB <sub>$i2$</sub>  of DHB-SM<sub>1</sub>. It can be observed that the estimated  $\hat{u}_{ci1}$  and  $\hat{u}_{ci2}$  are coinciding with  $u_{ci1}$  and  $u_{ci2}$ , respectively.

Fig. 7(a) shows the capacitor voltages in DHB-SM<sub>1</sub>~DHB-SM<sub>12</sub> in upper arm of phase A, while Fig. 7(b) shows the capacitor voltages in DHB-SM<sub>13</sub>~DHB-SM<sub>24</sub> in

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lower arm of phase A. It can be observed that the capacitor voltages can be well balanced at such a low switching frequency.

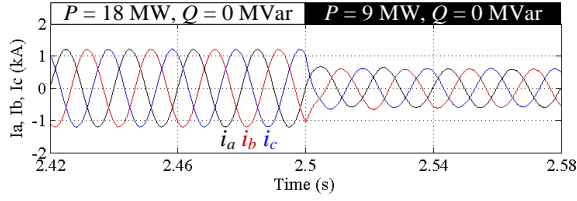


Fig. 5. AC-side current  $i_a$ ,  $i_b$  and  $i_c$  of DHB-SM based MMC.

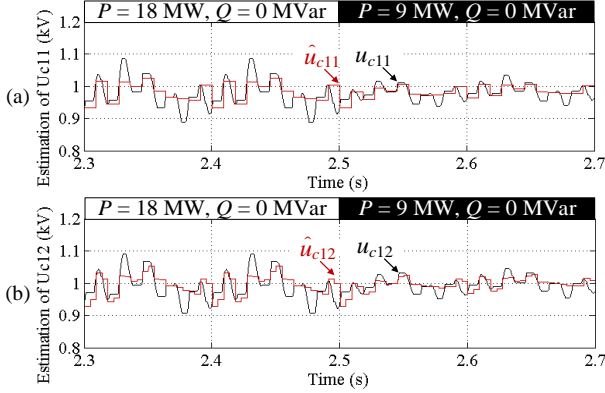


Fig. 6. Voltage estimation. (a) Estimated voltage  $\hat{u}_{c11}$  and capacitor voltage  $u_{c11}$  for HB<sub>11</sub> in DHB-SM<sub>1</sub> in upper arm of phase A. (b) Estimated voltage  $\hat{u}_{c12}$  and capacitor voltage  $u_{c12}$  for HB<sub>12</sub> in DHB-SM<sub>1</sub> in upper arm of phase A.

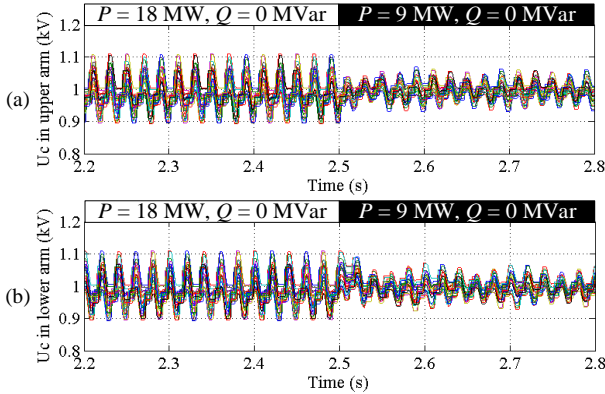


Fig. 7. Capacitor voltages in DHB-SM based MMC. (a) DHB-SM<sub>1</sub>~DHB-SM<sub>12</sub> in upper arm of phase A. (b) DHB-SM<sub>13</sub>~DHB-SM<sub>24</sub> in lower arm of phase A.

### B. Case II: HB-SM based MMC

Fig. 8 shows the ac-side current  $i_a$ ,  $i_b$  and  $i_c$  of the HB-SM based MMC. In comparison with Fig. 5, the current performance of the DHB-SM based MMC is almost the same to that of the HB-SM based MMC.

Fig. 9(a) shows the capacitor voltages in HB-SM<sub>1</sub>~HB-SM<sub>24</sub> in upper arm of phase A. Fig. 9(b) shows the capacitor voltages in HB-SM<sub>25</sub>~HB-SM<sub>48</sub> in lower arm of phase A. In comparison with Fig. 7, the capacitor voltage performance of the proposed DHB-SM based MMC is also similar to that of the HB-SM based MMC.

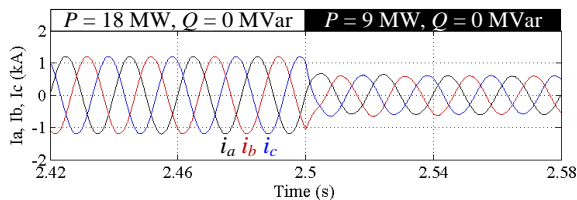


Fig. 8. AC-side current  $i_a$ ,  $i_b$  and  $i_c$  of HB-SM based MMC.

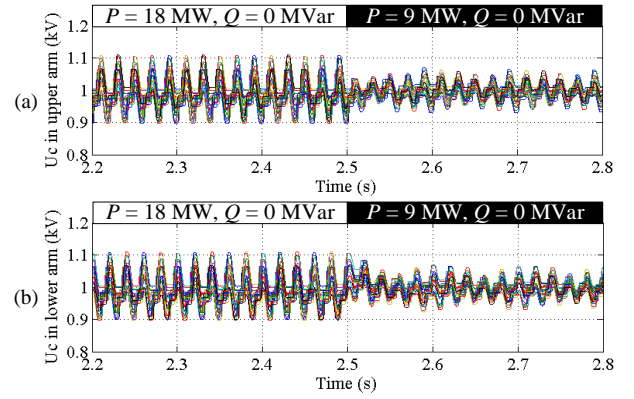


Fig. 9. Capacitor voltages in HB-SM based MMC. (a) HB-SM<sub>1</sub>~HB-SM<sub>24</sub> in upper arm of phase A. (b) HB-SM<sub>25</sub>~HB-SM<sub>48</sub> in lower arm of phase A.

## V. EXPERIMENTAL STUDIES

A single-phase DHB-SM based MMC prototype, as shown in Fig. 1(a), is built in the laboratory. Fig. 10 shows a photo of the experimental setup. The dc power supply SGA600/8 supports the dc link of the MMC. The IXFK48N36P is used as the switch/diode in each DHB-SM. The ac-side current control and VAC are implemented in a digital signal processor controller TMS32F28335. The voltage estimation, VBC and PSC-PWM are implemented in the FPGA device XC6SLX25. The system parameters are listed in TABLE V.

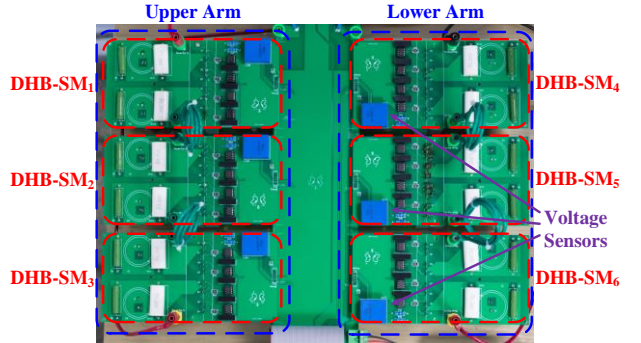


Fig. 10. Photo of the experimental setup.

TABLE V

Parameters for Experimental System	
Parameter	Value
DC link voltage $V_{dc}$ (V)	300
Rated frequency (Hz)	50
Number of DHB-SM per arm $N$	3
Rated capacitor voltage $u_{c0}$ (V)	50
SM capacitance (mF)	3.9
Arm inductance $L_s$ (mH)	1.8
Filter inductance $L_f$ (mH)	1.8
Load resistance $R_L$ ( $\Omega$ )	10
Carrier frequency $1/T_s$ (Hz)	400

Figs. 11~14 show the performance of the proposed MMC, where the ac-side current  $i_a$  is changed from 9 A to 4.5 A in a step. Fig. 11 shows  $i_a$ , upper arm current  $i_{au}$  and lower arm current  $i_{al}$ .

Fig. 12 shows the estimated capacitor voltage  $\hat{u}_{c11}$  and measured capacitor voltages  $u_{c11}$  for C<sub>11</sub> in HB<sub>11</sub> of DHB-SM<sub>1</sub>, as well as the estimated capacitor voltage  $\hat{u}_{c12}$  and measured capacitor voltages  $u_{c12}$  for C<sub>12</sub> in HB<sub>12</sub> of DHB-SM<sub>1</sub>, where the



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estimated capacitor voltages are output by digital-analog converter and recorded by the oscilloscope. It can be observed that the estimated  $\hat{u}_{c11}$  and  $\hat{u}_{c12}$  are coinciding with the measured  $u_{c11}$  and  $u_{c12}$ , respectively.

Fig. 13 shows the measured capacitor voltages  $u_{c11}$  and  $u_{c12}$  in DHB-SM<sub>1</sub> and measured capacitor voltages  $u_{c21}$  and  $u_{c22}$  in DHB-SM<sub>2</sub> in upper arm. Fig. 14 shows measured capacitor voltages  $u_{c41}$  and  $u_{c42}$  in DHB-SM<sub>4</sub> and measured capacitor voltages  $u_{c51}$  and  $u_{c52}$  in DHB-SM<sub>5</sub> in lower arm. It can be observed that the capacitor voltages in the proposed MMC can be well balanced with the estimated capacitor voltages in the proposed method.

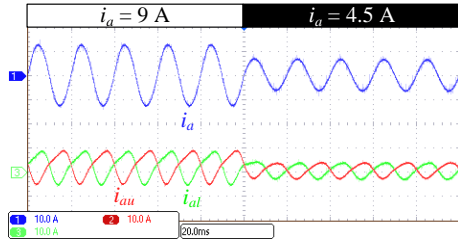


Fig. 11. AC-side current  $i_a$ , upper arm current  $i_{au}$  and lower arm current  $i_{al}$ .

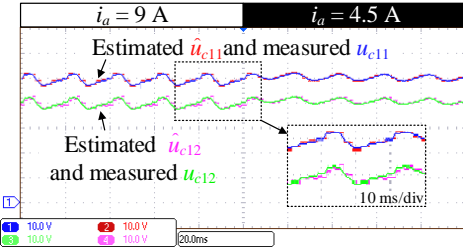


Fig. 12. Estimated voltage  $\hat{u}_{c11}$  and measured voltage  $u_{c11}$  for HB11 in DHB-SM<sub>1</sub> in upper arm. Estimated voltage  $\hat{u}_{c12}$  and measured voltage  $u_{c12}$  for HB12 in DHB-SM<sub>1</sub> in upper arm.

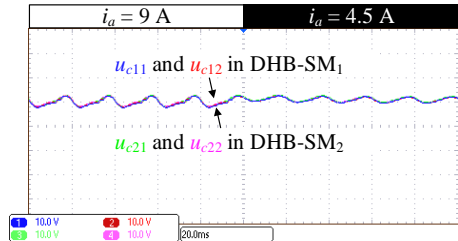


Fig. 13. Capacitor voltages for DHB-SM<sub>1</sub> and DHB-SM<sub>2</sub> in upper arm.

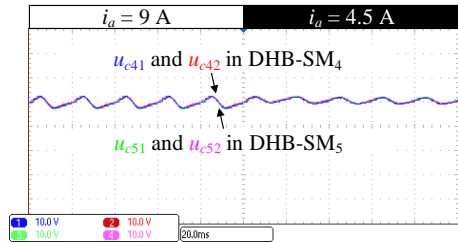


Fig. 14. Capacitor voltages for DHB-SM<sub>4</sub> and DHB-SM<sub>5</sub> in lower arm.

## VI. CONCLUSIONS

This letter proposes a DHB-SM for MMCs, where only one voltage sensor is equipped in each DHB-SM to measure the voltage between positive poles of two capacitors. The voltage estimation method is also proposed based on the sampled voltages at peak and valley of the carriers. The proposed MMC reduces the number of voltage sensors to half

in comparison with the conventional HB-SM based MMC. The simulation and experimental results confirm the effectiveness of the proposed DHB-SM based MMC and capacitor voltage estimation method.

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